

Lecturer: *D. J. Ivers*

Assignment 1 — Systems of Nonlinear Equations

Due 5pm Thursday 19th May.

Read the course messages for general information on assignments, the form your Assignment 1 file must take and how to submit it. This assignment is worth 4 marks.

1. Attached is a listing of the file `$mc3nm/ass1.inc`, which contains an incomplete main program for finding the real solution of the system of non-linear equations,

$$\begin{aligned}f_1(x_1, x_2) &= x_1x_2 - x_2^3 - 1 \\f_2(x_1, x_2) &= x_1^2x_2 + x_2 - 5\end{aligned}$$

near the point (2,3) using the Newton-Raphson method with damping (see (g) below). The equations are taken from Example 5.1 of the lecture notes. In `$mc3nm/ass1.inc` a question mark `?` indicates a missing single character, three horizontal dots `...` indicates a missing part or the missing whole of a line and three vertical dots indicates a missing block of code. **Copy** the file to your directory and complete the program to have the following features:

- (a) The integer variable `n` with the `parameter` attribute sets the size n of the problem.
- (b) The function `f`, solution `x` and increment `p` are the real one-dimensional arrays `f`, `x`, `p` of length n , and there are additional one-dimensional arrays `x0` and `f0` for the solution and function used in the damping. The Jacobian matrix `J` is a real two-dimensional array `J` of size $n \times n$.
- (c) The initial estimates of `X`, the relative error tolerance `tol` and the damping limit `kmax`, are input from the keyboard with prompts.
- (d) At each iteration of the damping counter, the iteration counter `i`, the iterates, the corresponding function values and the damping counter `k` are printed. Use an `F18.7` descriptor for all `real` variables. Each column of output must have an appropriate header.
- (e) The function `f` and the Jacobian matrix `J` are supplied by the subroutines `fun` and `jac`, internal to the main program `ass1`.
- (f) The linear system $\mathbf{Jp} = -\mathbf{f}$ is solved using the Gaussian elimination subroutine `solve` from Exercise Set 3.
- (g) The increment `p` is damped so that

$$\mathbf{x}_{i+1} = \mathbf{x}_i + \mathbf{p}/2^k$$

where $k \geq 0$ is the smallest value, such that

$$\|\mathbf{f}(\mathbf{x}_i + \mathbf{p}/2^{k-1})\|_2 \geq \|\mathbf{f}(\mathbf{x}_i)\|_2, \quad \|\mathbf{f}(\mathbf{x}_i + \mathbf{p}/2^k)\|_2 < \|\mathbf{f}(\mathbf{x}_i)\|_2.$$

The damping counter k is limited to $k \leq k_{\max}$, where k_{\max} is given by the integer variable `kmax` in the program. If $k_{\max} = 0$, the standard Newton-Raphson method is recovered.

(h) The relative change stopping test for vectors using the norm $\|\cdot\|_2$ is,

$$\|\mathbf{x}_{i+1} - \mathbf{x}_i\|_2 < \epsilon \|\mathbf{x}_{i+1}\|_2,$$

If this is satisfied, the Newton-Raphson iteration terminates, and the solution and function are printed with appropriate headers. The tolerance ϵ is given by the real variable `tol`. Note that the vector norm $\|\mathbf{x}\|_2$ is given in Fortran 90 by `sqrt(sum(x*x))`.

(i) A message is printed if there is no convergence of the (Newton-Raphson) i -loop in 24 iterations.

As a check on your program, compare your answers with those given in the notes.

2. Modify `fun` and `jac` in your program to find the solution of the equations,

$$\begin{aligned} x_1^2 - x_2 - 2.9 \ln |x_2| &= 0 \\ 2x_2^2 - x_1x_2 - 5x_2 + 1.1 &= 0, \end{aligned}$$

near (2,2).

(a) Take (2,2) as the starting approximation, a relative error tolerance $\epsilon = 5 \times 10^{-6}$ and use the two damping limits,

$$(i) \quad k_{\max} = 0 \qquad (ii) \quad k_{\max} = 10.$$

(b) Take (2.6,2) as the starting approximation, a relative error tolerance $\epsilon = 5 \times 10^{-6}$ and use the three damping limits,

$$(i) \quad k_{\max} = 0 \qquad (ii) \quad k_{\max} = 3$$

$$(iii) \quad k_{\max} = 10.$$

(c) Find the other zero using a relative error tolerance $\epsilon = 5 \times 10^{-6}$.

```

program ass1
integer, parameter :: n=?
????, dimension(n) :: f,...
????, dimension(?,?) :: ?
???????? :: singular

print*, 'Input starting approximation (x):'
read*, ?
print*, 'Input relative error tolerance (tol):'
...
print*, 'Input damping limit (kmax):'
...

print*, ' i          x1          ??          f1          ??          k'
???? fun

do i=1,?? ! Newton-Raphson iteration loop.
???? jac
call solve(?, -f, ?, ?, singular)
x0=x
f0=f
if (singular) then
    print*, 'Singular matrix'
else
    do k=0, kmax ! Damping loop.
        x = x0 + p/...
        call fun
        write(*, 10) i, ?, ?, k
10 format(I3, ??????, I3)
        if (sum(f*f) < sum(f0*f0)) exit ! Damping criterion.
    enddo

    if (sqrt(sum((x-x0)*(x-x0))) < ...) then
        print*, 'Solution:'
        print*, 'x = ', ?
        print*, 'f = ', ?
        stop
    endif
endif

enddo

print*, 'No convergence ...

stop
?????????
!-----
subroutine fun

f(1) = ...
...

end ...

```

```
!-----  
subroutine jac  
J(1,1) = ...  
:::  
  
...  
!-----  
??? program ????  
!=====
```

```
subroutine solve(A,b,x,n,singular)  
:  
:
```