MATH 2022 Linear and Abstract Algebra
LECTURE 05 Wednesday 04/03/2020

the transpose of M, is the nxm matrix

e.g. Working over IR, put
$$M = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}, \quad \Sigma = \begin{bmatrix} 1 \\ 2 \end{bmatrix}.$$

Then
$$M^{T} = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}, \quad y^{T} = \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}$$

e.g. Working over 1R, put
$$M = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}, \quad S = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}.$$

$$M = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}, \quad \mathcal{D}$$

$$M = \begin{bmatrix} 4 & 5 & 6 \end{bmatrix} \qquad 5 =$$

Then
$$M^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$
, $S^T = \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}$,

$$M = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 11 \end{bmatrix}$$

Then
$$M^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$
, $S_{\infty}^T = \begin{bmatrix} 1 & 4 \\ 3 & 6 \end{bmatrix}$

$$M = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \quad \mathcal{L} =$$

 $\mathcal{L}^{\mathsf{T}} \mathsf{M}^{\mathsf{T}} = \begin{bmatrix} 1 & -1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix} = \begin{bmatrix} 5 & 11 \end{bmatrix} = \begin{pmatrix} \mathsf{M} \mathcal{L} \end{pmatrix}^{\mathsf{T}}.$

In general, when sums and products are defined,

$$(A + B)^{T} = A^{T} + B^{T}, \quad (A^{T})^{T} = A,$$

$$(AB)^{T} = B^{T}A^{T}.$$

$$\int_{a}^{b} A^{T} dx = A^{T} + B^{T} + B^{T}$$

$$\int_{a}^{b} A^{T} dx = A^{T} + B^{T}$$

Solving systems of equations:

All the familiar techniques carry over to matrices where entries come from any fixel field F.

A system of m linear equations in a variables $x_1, ..., x_n$ has the form

$$a_{11} \times_{1} + a_{12} \times_{2} + \dots + a_{1n} \times_{n} = b_{1}$$
 $a_{21} \times_{1} + a_{22} \times_{2} + \dots + a_{2n} \times_{n} = b_{2}$
 \vdots
 $a_{n_{1}} \times_{1} + a_{n_{2}} \times_{2} + \dots + a_{n_{n}} \times_{n} = b_{n}$

where ai, , b; are constants from F.

The system has augmented matrix

which is an abbreviation for the matrix equation

$$M = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1N} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m_1} & a_{m_2} & \cdots & a_{m_N} \end{bmatrix}, \quad \chi = \begin{bmatrix} \chi_1 \\ \chi_2 \\ \vdots \\ \chi_N \end{bmatrix}, \quad b = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

To solve the system:

- perform Gaussian elimination using elementary row operations (e.r.o.s)

- to convert the augmented matrix into row echelon form

- and then apply back substitution

- assigning parameters to non-leading variables.

Three types of e.r.o.'s:

(1) interchanging ith and jth rows, denoted by $R_i \longleftrightarrow R_j$

multiplying the ith row by a nonzero constant $\lambda \in F$, denoted by $R_i \longrightarrow \lambda R_i$

(3) adding a multiple of the jth row to the ith row, denoted by

 $R_{:} \rightarrow R_{:} + \lambda R_{:}$

For a matrix to be in row echelon form:

- (a) rows of zeros appear at the bottom,
- (b) first nonzero (leading) entries of consecutive rows appear further to the right,
- c) leading entries of rows are equal to 1.

in practice, (c) is often relaxed

For a matrix to be in row echelon form : (a) rows of zeros appear at the bottom, (b) first nonzero (leading) entries of consecutive rows appear further to the right, (c) leading entries of rows are equal to 1. To be in reduced row echelon form, we also require (d) entries above (and below) leading entries are zero.)

For a matrix to be in row echelon form : (a) rows of zeros appear at the bottom, (b) first nonzero (leading) entries of consecutive rows appear further to the right leading entries of rows are equal to 1 To be in reduced row echelon form, we also (d) entries above (and below) leading entries are zero. can be applied simplifies if (d) holds

Theorem (difficult): A given matrix can be row reduced to one and only one matrix in reduced row echelon form.

(Row cubelon forms that are not reduced need not be unique.)

A system is inconsistent (has no solution) iff at some stage during row reduction a row of zeros oppears, followed by nonzero k to the right

Example: Solve the following over R and
$$\mathbb{Z}_{7}$$
:

 $x_{1} + x_{2} + x_{3} + x_{4} + x_{5} = 2$
 $x_{1} - x_{2} + x_{3}$
 $x_{1} + 5x_{2} + x_{3} + 3x_{4} + 3x_{5} = 3$

Solution:

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 2 \\ 1 & -1 & 1 & 0 & -1 \\ 1 & 5 & 1 & 3 & 3 & 3 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 0 & -2 & 0 & -1 & -2 & -2 \\ 0 & 4 & 0 & 2 & 2 & 1 \end{bmatrix}$$
 $R_{2} \rightarrow R_{3} - R_{1}$

$$R_{3} \rightarrow R_{3} - R_{1}$$

$$R_{4} \rightarrow R_{3} - R_{1}$$

$$R_{5} \rightarrow R_{3} - R_{1}$$

$$R_{5} \rightarrow R_{3} - R_{1}$$

$$R_{5} \rightarrow R_{3} - R_{1}$$

Solution: $\begin{bmatrix} 1 & 1 & 1 & 1 & 2 \\ 1 & -1 & 1 & 0 & -1 & 0 \\ 1 & 5 & 1 & 3 & 3 & 3 & 3 & 0 \\ \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 2 \\ 0 & -2 & 0 & -1 & -2 & -2 \\ 0 & 4 & 0 & 2 & 2 & 1 & 1 \\ R_3 \rightarrow R_3 - R_1 & R_2 - R_1 & R_3 - R_1 & R_2 - R_1 & R_2 - R_1 \\ \end{bmatrix}$ ~ [| 0 | ½ 0 | 1] R, - R, - R₂
~ [0 0 0 0 0 1 | 3/2] R₃ - - 2 R₃ in reduced row echelon form

Solution: $\begin{bmatrix} 1 & 1 & 1 & 1 & 2 \\ 1 & -1 & 1 & 0 & -1 & 0 \\ 1 & 5 & 1 & 3 & 3 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 3 \end{bmatrix}$ giving an equivalent system: x_1 $+ x_3 + \frac{1}{2}x_4 = 1$ $= -\frac{1}{2}$ $x_5 = \frac{3}{2}$ The leading variables are x, x2, x5. The non-leading voriables are x3, x4.

The leading variables are
$$x_1$$
, x_2 , x_3 = $\frac{3}{2}$.

The non-leading variables are x_3 , x_4 .

Back substitution: $x_5 = \frac{3}{2}$, $x_4 = t$, $x_3 = s$,

 $x_2 = -\frac{1}{2} - \frac{1}{2}x_4 = -\frac{1}{2} - \frac{1}{2}$.

Solution:

Back substitution:
$$x_{5} = \frac{3}{2}$$
, $x_{4} = t$, $x_{3} = S$,

 $x_{2} = -\frac{1}{2} - \frac{1}{2}x_{4} = -\frac{1}{2} - \frac{1}{2}$,

 $x_{1} = 1 - x_{3} - \frac{1}{2}x_{4} = 1 - S - \frac{1}{2}$,

Solution over IR:

 $x_{1} = 1 - S - \frac{1}{2}$, $x_{2} = -\frac{1}{2} - \frac{1}{2}$, $x_{3} = S$, $x_{4} = t$, $x_{5} = \frac{3}{2}$

where $S, t \in \mathbb{R}$.

Solution set: $\{(1-S-\frac{1}{2}, -\frac{1}{2}-\frac{1}{2}, S, t, \frac{3}{2}) \mid S, t \in \mathbb{R}\}$.

Solution: Solution over R: x, = 1-8-\(\frac{1}{2}\), x_= -\(\frac{1}{2}\)-\(\frac{1}{2}\), x_3 = S, x_4 = \(\frac{1}{2}\), x_5 = \(\frac{3}{2}\) where s,telk. Solution set: { (1-5-te, -2-te, s,t, 3/2) | s,t FR} Solution over \mathbb{Z}_7 : all fractions involved dividing by 2, sensible in \mathbb{Z}_7 , so same solution description holds over Z, but simplifies because (= 4) in Z.

Solution set over IR: {(1-5-42, -1-42, s, t, 3/2) | s, t FR} Solution over \mathbb{Z}_7 : all fractions involved dividing by 2, sensible in \mathbb{Z}_7 , so same solution description holds over Z, but simplifies because (= 4) in Z. Solution set over 2; { (1+6s+3t, 3+3t, s,t,5) \ s,t \ Z_{7}} The solution set is infinite over IR, but has $7^2=49$ solutions over \mathbb{Z}_7 .