

# MATH1902 Linear Algebra

Lecture 23  
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Lecture Notes: *Linear Algebra* by R. B. Howlett  
Available from Kopystop  
(36 Mountain Street, Broadway)

Lecturer: Associate Professor D. E. Taylor  
Room: 711, Carlaw Building  
Office Hour: Tuesday 1pm – 2pm

Enquiries to: First Year Mathematics Office,  
5th floor, Carlaw Building

Web:

[www.maths.usyd.edu.au/u/UG/JM/MATH1902/](http://www.maths.usyd.edu.au/u/UG/JM/MATH1902/)

# Objectives

- Calculating eigenvalues and eigenvectors
- The characteristic equation

# Review

Recall that

- for a square matrix  $A$  with  $n$  rows and  $n$  columns, the matrix equation  $A\mathbf{x} = \mathbf{0}$  has a **non-zero** solution for  $\mathbf{x}$  if and only if  $A$  is **not** invertible. (If  $A$  is invertible there is a *unique* solution, namely  $\mathbf{x} = \mathbf{0}$ ).
- A square matrix  $A$  is invertible if and only if  $\det A \neq 0$ .
- An **eigenvalue** of  $A$  is a scalar  $\lambda$  such that  $A\mathbf{v} = \lambda\mathbf{v}$  for some *non-zero* column vector  $\mathbf{v}$ .
- An **eigenvector** of  $A$  is a non-zero column vector  $\mathbf{v}$  such that  $A\mathbf{v} = \lambda\mathbf{v}$  for some scalar  $\lambda$ .
- Every non-zero multiple of an eigenvector  $\mathbf{v}$  of  $A$  with eigenvalue  $\lambda$  is also an eigenvector of  $A$  with eigenvalue  $\lambda$ .

# Determinants and eigenvalues

In the previous lecture we considered the problem of finding all the eigenvectors and eigenvalues of

$$A = \begin{bmatrix} -1 & 3 & 1 \\ 1 & 5 & 5 \\ 0 & -3 & -2 \end{bmatrix}.$$

That is, we solved the matrix equation

$$\begin{bmatrix} -1 & 3 & 1 \\ 1 & 5 & 5 \\ 0 & -3 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \lambda \begin{bmatrix} x \\ y \\ z \end{bmatrix}.$$

When we write this out in full and collect terms on the left hand side, it becomes

$$\begin{aligned} (-1 - \lambda)x + 3y + z &= 0 \\ x + (5 - \lambda)y + 5z &= 0 \\ -3y + (-2 - \lambda)z &= 0, \end{aligned}$$

that is

$$(A - \lambda I_3)\mathbf{v} = \mathbf{0}, \quad \text{where } \mathbf{v} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}.$$

The equation  $(A - \lambda I_3)\mathbf{v} = \mathbf{0}$  has a non-zero solution if and only if  $(A - \lambda I_3)$  is **not** invertible. This is the case if and only if  $\det(A - \lambda I_3) = 0$ .

Expanding down the first column, the determinant is

$$\begin{aligned}
 & \begin{vmatrix} -1 - \lambda & 3 & 1 \\ 1 & 5 - \lambda & 5 \\ 0 & -3 & -2 - \lambda \end{vmatrix} \\
 &= (-1 - \lambda) \begin{vmatrix} 5 - \lambda & 5 \\ -3 & -2 - \lambda \end{vmatrix} - \begin{vmatrix} 3 & 1 \\ -3 & -2 - \lambda \end{vmatrix} \\
 &= (-1 - \lambda)((5 - \lambda)(-2 - \lambda) + 15) \\
 &\quad - (3(-2 - \lambda) + 3) \\
 &= (-1 - \lambda)(-10 - 3\lambda + \lambda^2 + 15) - (-6 - 3\lambda + 3) \\
 &= -5 - 2\lambda + 2\lambda^2 - \lambda^3 + 3 + 3\lambda \\
 &= -\lambda^3 + 2\lambda^2 + \lambda - 2 \\
 &= -(\lambda - 1)(\lambda + 1)(\lambda - 2)
 \end{aligned}$$

It follows that the eigenvalues of  $A$  are 1,  $-1$  and 2. To find the eigenvectors we solve  $(A - \lambda I_3)\mathbf{v} = \mathbf{0}$  for each possible eigenvalue. As a check we note that there *must* be a non-zero solution.

# The eigenvectors

When  $\lambda = 1$  the eigenvectors are the solutions of  $(A - I_3)\mathbf{v} = \mathbf{0}$ .

To solve these equations we can use elementary row operations to reduce the matrix to an echelon form.

The right hand side of the augmented matrix is a column of zeros. Row operations cannot change this and so there is no need to write it down again and again.

$$\begin{aligned} \begin{bmatrix} -2 & 3 & 1 \\ 1 & 4 & 5 \\ 0 & -3 & -3 \end{bmatrix} &\xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 4 & 5 \\ -2 & 3 & 1 \\ 0 & -3 & -3 \end{bmatrix} \\ &\xrightarrow{R_2 := R_2 + 2R_1} \begin{bmatrix} 1 & 4 & 5 \\ 0 & 11 & 11 \\ 0 & -3 & -3 \end{bmatrix} \\ &\xrightarrow{\substack{R_2 := \frac{1}{11}R_2 \\ R_3 := -\frac{1}{3}R_3}} \begin{bmatrix} 1 & 4 & 5 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \\ &\xrightarrow{R_3 := R_3 - R_2} \begin{bmatrix} 1 & 4 & 5 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

Putting  $z = t$  we find that  $y = -t$  and  $x = -t$ . Thus  $\mathbf{v} = t \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$ .

When  $\lambda = -1$  the eigenvectors are the solutions of  $(A + I_3)\mathbf{v} = \mathbf{0}$ .

Once again we use elementary row operations to solve the equations.

$$\begin{aligned} \begin{bmatrix} 0 & 3 & 1 \\ 1 & 6 & 5 \\ 0 & -3 & -1 \end{bmatrix} &\xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 6 & 5 \\ 0 & 3 & 1 \\ 0 & -3 & -1 \end{bmatrix} \\ &\xrightarrow{R_3 := R_3 + R_2} \begin{bmatrix} 1 & 6 & 5 \\ 0 & 3 & 1 \\ 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

To avoid fractions, put  $z = 3t$ . Then  $y = -t$  and  $x = -9t$ . Thus the eigenvectors are  $\mathbf{v} = t \begin{bmatrix} -9 \\ -1 \\ 3 \end{bmatrix}$ , where  $t \neq 0$ .

Finally we have the case  $\lambda = 2$ .

$$\begin{aligned} \begin{bmatrix} -3 & 3 & 1 \\ 1 & 3 & 5 \\ 0 & -3 & -4 \end{bmatrix} &\xrightarrow{R_1 \leftrightarrow R_2} \begin{bmatrix} 1 & 3 & 5 \\ -3 & 3 & 1 \\ 0 & -3 & -4 \end{bmatrix} \\ &\xrightarrow{R_2 := R_2 + 3R_1} \begin{bmatrix} 1 & 3 & 5 \\ 0 & 12 & 16 \\ 0 & -3 & -4 \end{bmatrix} \end{aligned}$$

Again to avoid fractions we put  $z = 3t$  so that  $y = -4t$  and  $x = -3t$ . Thus the eigenvectors are the non-zero multiples of  $\begin{bmatrix} -3 \\ -4 \\ 3 \end{bmatrix}$ .

## The characteristic equation

The **characteristic equation** of a square matrix  $A$  is the equation

$$\det(A - xI) = 0$$

where  $x$  is the unknown.

For example, we found the characteristic equation of the matrix  $A$  of the previous example to be  $-(x - 1)(x + 1)(x - 2) = 0$ .

The eigenvalues of  $A$  are the roots of the characteristic equation.

The expression  $\det(A - xI)$  is called the **characteristic polynomial** of  $A$ .

For example, the characteristic polynomial of  $\begin{bmatrix} 1 & 1 \\ 1 & 5 \end{bmatrix}$  is

$$\begin{vmatrix} 1 - x & 1 \\ 1 & 5 - x \end{vmatrix} = (1 - x)(5 - x) - 1 = x^2 - 6x + 4$$