

## Math2061: Linear Mathematics Component

- Geoff Phillips, Carslaw 486
- Math2061 consists of two separate modules:  
Linear Mathematics and Vector Calculus.
- Math2061 web page  
[www.maths.usyd.edu.au/u/UG/SS/SS2061](http://www.maths.usyd.edu.au/u/UG/SS/SS2061)

Lectures, tutorials, practice classes for six weeks

- **Classes:**  

3 hours of lectures	Mon 2pm-4pm and Tues 2pm
1 Practice Session	Tues 3pm
1 Tutorial	Mon 4pm or Tues 4pm
- **Consultations:** by arrangement
- **Assessment**  

65%:	Exam at end of semester 1.
10%:	Quiz (on week 3)
10%:	Quiz (on week 5)
10%:	Assignment (due week 5).
5%:	Tutorial participation.

## Textbooks and references

- **Textbook**

[Jenny Henderson](#) **Math2061: Linear Mathematics**

Available from Kopystop  
(55 Mountain street, Broadway).

- **References**

[David Poole](#) *Linear Algebra: A Modern Introduction* (*full version*)

For Revision of First Year:

[David Easdown](#) *A First Course in Linear Algebra*

The *Little Blue Book* by [Britton and Henderson](#) is a good summary of First Year calculus and algebra.

What is *linear mathematics* about?

- Linear mathematics is one of the foundations of modern mathematics.
- It is important theoretically because so many apparently different processes in the natural world have the same *linear structure* – they are *vector spaces*.
- Many non-linear processes are often so complicated that they are modelled by linear approximations as a first step towards their understanding. Numerical solutions to many linear problems can be found quickly and accurately, using the theory from this course.
- We will study the beginnings of vector space theory and discuss some of the applications.
- Preparatory work: You should revise the following topics from Math1002 or Math1014: equations of lines and planes in space, the solution of systems of linear equations, reduced row echelon form of a matrix, elementary matrices, the calculation of eigenvectors and eigenvalues for  $2 \times 2$  and  $3 \times 3$  matrices.

### Course objectives

- To introduce the basic concepts of vector spaces.
- To demonstrate how abstract theory can be applied to concrete problems in science and engineering.
- To develop logical thinking and ability to analyse logical arguments.

### Outcomes

At the end of this unit of study you should be able to:

- solve a system of linear equations,
- apply the subspace test in several different vector spaces,
- calculate the span of a given set of vectors in various vector spaces,
- test vectors for linear independence and dependence,
- find a polynomial of minimum degree that fits a set of points exactly,

- find bases of the fundamental subspaces of a matrix,
- diagonalise an  $n \times n$  matrix (for small  $n$ ),
- apply diagonalisation to solve recurrence relations and systems of DEs.
- identify linear transformations between vector spaces,

**Your job!** For best results and maximum enjoyment in this course you should:

- make every effort to attend all the lectures, practice sessions and tutorials.
- Do as many problems as you can, and make sure you work through the solutions to the tutorial exercises each week.
- Read and understand the reference books and your own lecture notes!
- Come to the lecturers with your questions at consultation times. We are there help you.

## Weekly outline of course

- Week 1: Linear systems, Gaussian elimination, vector spaces.
- Week 2: Vector spaces and subspaces, Linear combinations and linear independence, Span of a set of vectors.
- Week 3: Basis and dimension of a vector space, Linear transformations as maps between vector spaces, Column space, Null space and Rank of a matrix.
- Week 4: Geometric interpretation of matrix transformations. Eigenvalues and eigenvectors, diagonalisation of a matrix, eigenvalues of symmetric matrices.
- Week 5: Mathematical modelling and eigenvalues, Leslie population model, Linear recurrence relations.
- Week 6: Systems of linear differential equations, More on eigenvalues and eigenvectors, Review of previous examinations.

## Linear equations—revision

A **system of  $m$  linear equations** in the unknowns  $x_1, x_2, \dots, x_n$ , is a set of equations:

$$\begin{cases} a_{11}x_1 + \dots + a_{1n}x_n & = b_1 \\ \vdots & \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n & = b_m \end{cases}$$

This can be written as a single matrix equation:

$$\begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix}$$

- Systems of linear equations can be solved using **Gaussian elimination**
- **Gaussian elimination** is the fundamental tool which underpins almost everything in this course. You should revise your notes from Math1002 or Math1014 and *make sure that you understand how it works*.

## Gaussian elimination—Example 1

**Example** In the commercial preparation of nitric acid, one of the steps is the production of nitrogen dioxide:



We want to balance this equation.

**Suppose:**  $w$  molecules of  $\text{NH}_3$  yield  
 $y$  molecules of  $\text{NO}_2$   
 $x$  molecules of  $\text{O}_2$  and  
 $z$  molecules of  $\text{H}_2\text{O}$

Balancing the atoms of the various elements we get

$$\text{Nitrogen} \quad w = y$$

$$\text{Hydrogen} \quad 3w = 2z$$

$$\text{Oxygen} \quad 2x = 2y + z$$

This corresponds to the system of linear equations:

$$\begin{array}{rcccc} w & & -y & & = & 0 \\ 3w & & & -2z & = & 0 \\ & 2x & -2y & -z & = & 0 \end{array}$$

We have the system of linear equations:

$$\begin{array}{rcccc} w & & -y & & = & 0 \\ 3w & & & -2z & = & 0 \\ & 2x & -2y & -z & = & 0 \end{array}$$

So we have the following **general solution**:

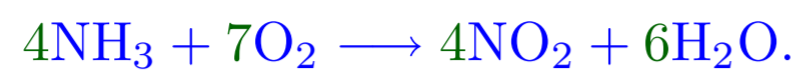
$$\begin{array}{l} w = \frac{2}{3}t \\ x = \frac{1}{3}t \\ y = \frac{2}{3}t \\ z = t \in \mathbb{R} \end{array} \quad \text{or} \quad \begin{bmatrix} w \\ x \\ y \\ z \end{bmatrix} = \begin{pmatrix} \frac{2}{3}t \\ \frac{1}{3}t \\ \frac{2}{3}t \\ t \end{pmatrix}$$

Taking  $t = 6$  we get the **particular solution**:

$$\begin{array}{l} w = 4 \\ x = 7 \\ y = 4 \\ z = 6 \end{array}$$

We take  $z = 6$  so that the solution is *integer* valued.

Therefore, the balanced equation is:



Gaussian Elimination Example 2

Solve the equations: 
$$\begin{cases} x + 4y + 7z = 7 \\ 2x + 5y + 8z = 11 \\ 3x + 6y + 9z = 15 \end{cases}$$

Again, we write down the augmented matrix and apply row operations:

$$\begin{aligned} \left[ \begin{array}{ccc|c} 1 & 4 & 7 & 7 \\ 2 & 5 & 8 & 11 \\ 3 & 6 & 9 & 15 \end{array} \right] & \xrightarrow{\substack{R_2=R_2-2R_1 \\ R_3=R_3-3R_1}} \left[ \begin{array}{ccc|c} 1 & 4 & 7 & 7 \\ 0 & -3 & -6 & -3 \\ 0 & -6 & -12 & -6 \end{array} \right] \\ & \xrightarrow{R_3=R_3+2R_2} \left[ \begin{array}{ccc|c} 1 & 4 & 7 & 7 \\ 0 & -3 & -6 & -3 \\ 0 & 0 & 0 & 0 \end{array} \right] \\ & \xrightarrow{R_2=-\frac{1}{3}R_2} \left[ \begin{array}{ccc|c} 1 & 4 & 7 & 7 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right] \end{aligned}$$

So the general solution is  $z = t$ ,  $y = 1 - 2z = 1 - 2t$  and  $x = 7 - 4y - 7z = 3 + t$ .

That is, 
$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 3+t \\ 1-2t \\ t \end{bmatrix} = \underbrace{\begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix}}_{\text{particular solution}} + t \underbrace{\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}}_{\text{general solution}},$$

where  $t \in \mathbb{R}$ .

How many solutions are there?

Consider the matrix equation:  $Ax = b$ .

How many solutions can this equation have?

From last year we know that, depending on  $A$  and  $b$ , this equation can have:

- **no solutions**

E.g. 
$$\left[ \begin{array}{cc|c} 1 & 1 & 1 \\ 1 & 1 & 2 \end{array} \right] \iff \left[ \begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 0 & 1 \end{array} \right]$$
  
 inconsistent

- **exactly one solution**

E.g. 
$$\left[ \begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 1 & 2 \end{array} \right] \iff \left[ \begin{array}{cc|c} 1 & 0 & -1 \\ 0 & 1 & 2 \end{array} \right] \iff$$
  

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

- an infinite number of solutions

E.g.  $\left[ \begin{array}{cc|c} 1 & 1 & 1 \\ 0 & 0 & 0 \end{array} \right] \iff \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1-t \\ t \end{bmatrix}, \text{ for } t \in \mathbb{R}.$

When does a system of equations have a solution?

**Claim 1** Suppose that  $A = (a_{ij})$  is an  $n \times m$  matrix. Then the matrix equation  $Ax = b$  has a solution if and only if  $b$  can be written as a linear combination of the columns of  $A$ .

- Write

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1m} \\ a_{21} & a_{22} & \cdots & a_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nm} \end{bmatrix} = \begin{bmatrix} a_1 & a_2 & \cdots & a_m \end{bmatrix},$$

where  $a_i = \begin{bmatrix} a_{1i} \\ \vdots \\ a_{ni} \end{bmatrix}$  is column  $i$  of  $A$ .

- We need to show that  $b$  is a solution if and only if  $b = \lambda_1 a_1 + \lambda_2 a_2 + \cdots + \lambda_m a_m$ , for some numbers  $\lambda_1, \dots, \lambda_m \in \mathbb{R}$ .
- First, suppose that  $b = \lambda_1 a_1 + \lambda_2 a_2 + \cdots + \lambda_m a_m$ .

Then, because of how matrix multiplication works,

$$b = \lambda_1 \begin{bmatrix} a_{11} \\ \vdots \\ a_{n1} \end{bmatrix} + \lambda_2 \begin{bmatrix} a_{21} \\ \vdots \\ a_{n2} \end{bmatrix} + \cdots + \lambda_m \begin{bmatrix} a_{1m} \\ \vdots \\ a_{nm} \end{bmatrix} \quad \text{So}$$

$b$  is the solution corresponding to  $x = \begin{bmatrix} \lambda_1 \\ \vdots \\ \lambda_m \end{bmatrix}$

Conversely, suppose that  $y$  is a solution to  $Ax = b$ .

Expanding the equation  $b = Ay$  we discover that:

$$\begin{aligned} \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix} &= \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1m} \\ a_{21} & a_{22} & \cdots & a_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nm} \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} \\ &= \begin{bmatrix} y_1 a_{11} + y_2 a_{12} + \cdots + y_m a_{1m} \\ y_1 a_{21} + y_2 a_{22} + \cdots + y_m a_{2m} \\ \vdots \\ y_1 a_{n1} + y_2 a_{n2} + \cdots + y_m a_{nm} \end{bmatrix} \\ &= y_1 \begin{bmatrix} a_{11} \\ \vdots \\ a_{n1} \end{bmatrix} + y_2 \begin{bmatrix} a_{21} \\ \vdots \\ a_{n2} \end{bmatrix} + \cdots + y_m \begin{bmatrix} a_{1m} \\ \vdots \\ a_{nm} \end{bmatrix} \\ &= y_1 a_1 + y_2 a_2 + \cdots + y_m a_m \end{aligned}$$

So the solution  $y$  can be written as linear combination of the columns of  $A$ , as claimed.

We have now seen that:

- **Claim 1** Suppose that  $A = (a_{ij})$  is an  $n \times n$  matrix. The matrix equation  $Ax = b$  has a solution if and only if  $b$  can be written as a linear combination of the columns of  $A$ .
- Going back to Example 2 we saw that the general solution of the augmented matrix equation

$$\left[ \begin{array}{ccc|c} 1 & 4 & 7 & 7 \\ 2 & 5 & 8 & 11 \\ 3 & 6 & 9 & 15 \end{array} \right]$$

is  $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 3+t \\ 1-2t \\ t \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$ , where  $t \in \mathbb{R}$ .

Reading ‘backwards’,

$$b = \begin{bmatrix} 7 \\ 11 \\ 15 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + 1 \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} + 0 \begin{bmatrix} 7 \\ 8 \\ 9 \end{bmatrix}.$$