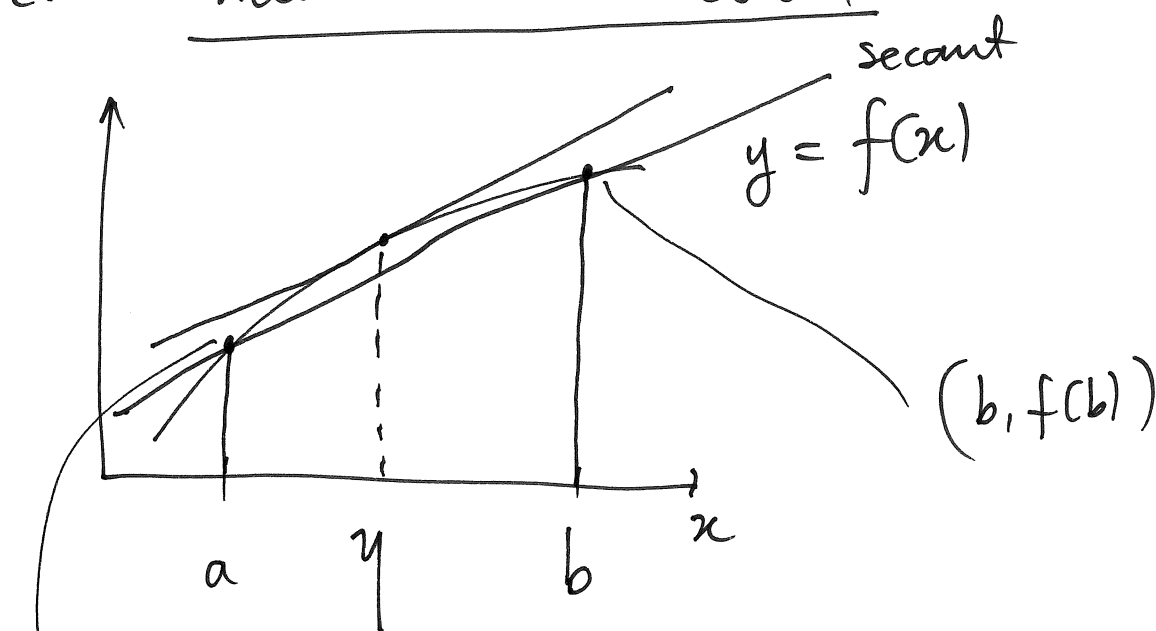


§1.2 Background Mathematics

2. Mean Value Theorem



$(a, f(a))$

$$\text{slope of secant} = \frac{f(b) - f(a)}{b - a}$$

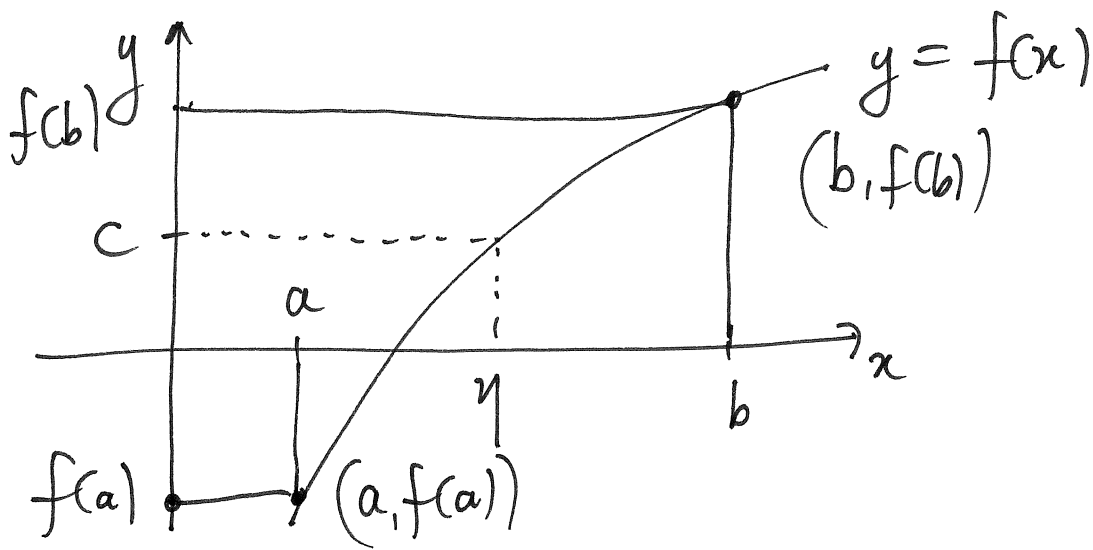
$$= \text{slope of tangent at } \eta, \quad a < \eta < b$$

$$= f'(\eta)$$

$$f(b) = f(a) + f'(\eta)(b - a)$$

$f \in C'[a, b]$, i.e. f is continuous on the interval $a \leq x \leq b$; $f' \equiv \frac{df}{dx}$ is continuous on $a \leq x \leq b$.

3. Intermediate Value Theorem



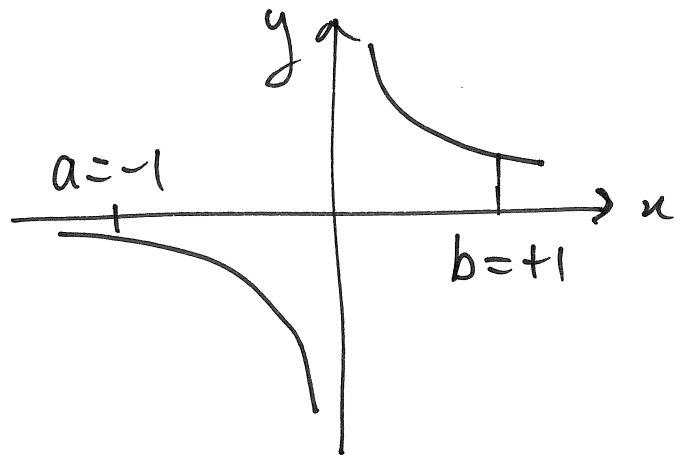
If $f \in C[a, b]$, i.e. f is continuous on $a \leq x \leq b$, and $f(a) < c < f(b)$, then there exists η , $a < \eta < b$, such that $f(\eta) = c$.

Existence theorem for zero of $f(x)$:

if $f(a)f(b) < 0$, i.e. f changes sign between a, b , then there exists x^* , $a < x^* < b$, such that $f(x^*) = 0$. This requires $f \in C[a, b]$.

Counter-example : if f is not
continuous this is false.

Eg $y = \frac{1}{x}$



$$f(a) = -1$$

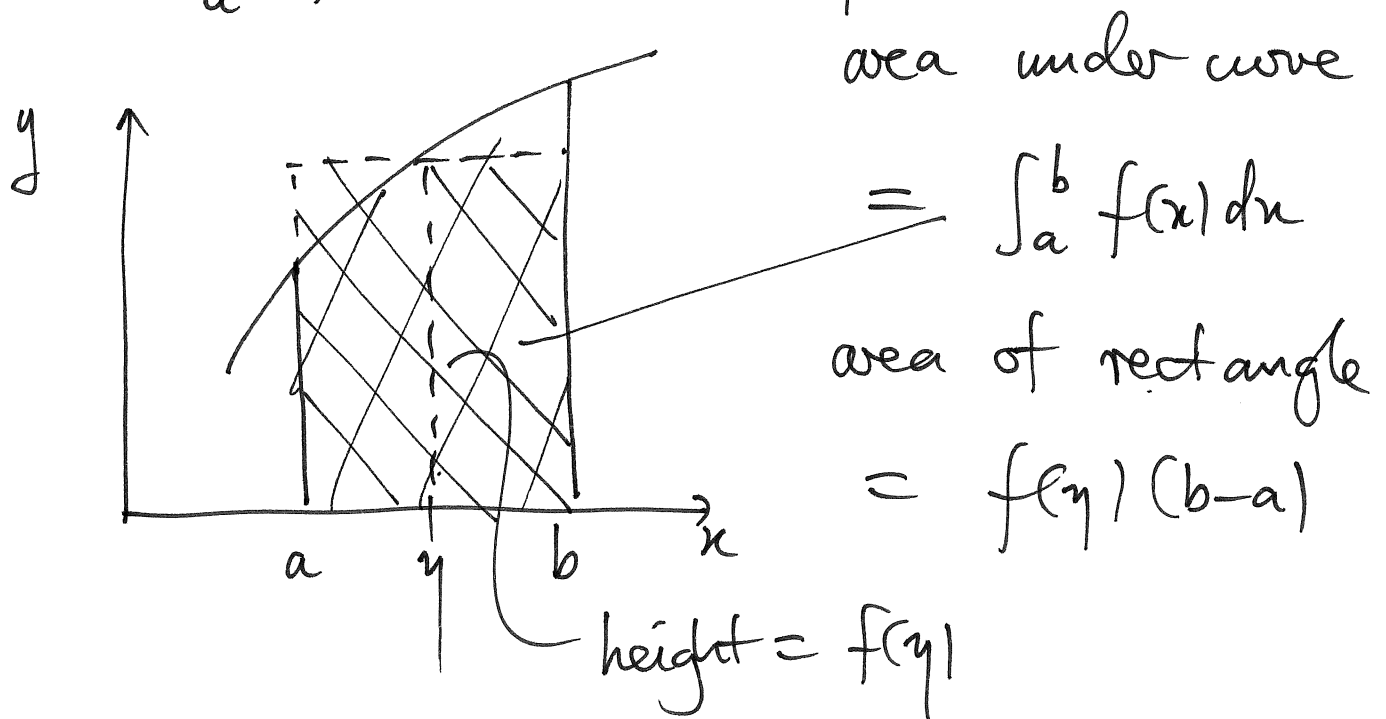
$$f(b) = +1$$

but $f(\eta) \neq 0$ for any $\eta, -1 < \eta < 1$.

4 Mean Value Theorem for Integral Calculus

Let $f \in C[a, b]$, then there exists η , $a < \eta < b$, such that

$$\int_a^b f(x) dx = f(\eta)(b-a)$$



Generalised Theorem

Let $f \in C[a, b]$, $g \geq 0$ on $[a, b]$

There exists η , $a < \eta < b$, such that

$$\int_a^b f(x)g(x) dx = f(\eta) \int_a^b g(x) dx$$

Proof: The function f must satisfy

$$\min_{[a,b]} f \leq f(x) \leq \max_{[a,b]} f$$

for all $x \in [a, b]$. Multiply by $g(x) \geq 0$,

$$g(x) \min f \leq f(x)g(x) \leq g(x) \max f$$

Integrate

$$\begin{aligned} \min f \int_a^b g(x) dx &\leq \int_a^b f(x)g(x) dx \\ &\leq \max f \int_a^b g(x) dx \end{aligned}$$

Wlog $\int_a^b g(x) dx > 0$, so

$$\min_{[a,b]} f \leq \frac{\int_a^b f(x)g(x) dx}{\int_a^b g(x) dx} \leq \max_{[a,b]} f$$

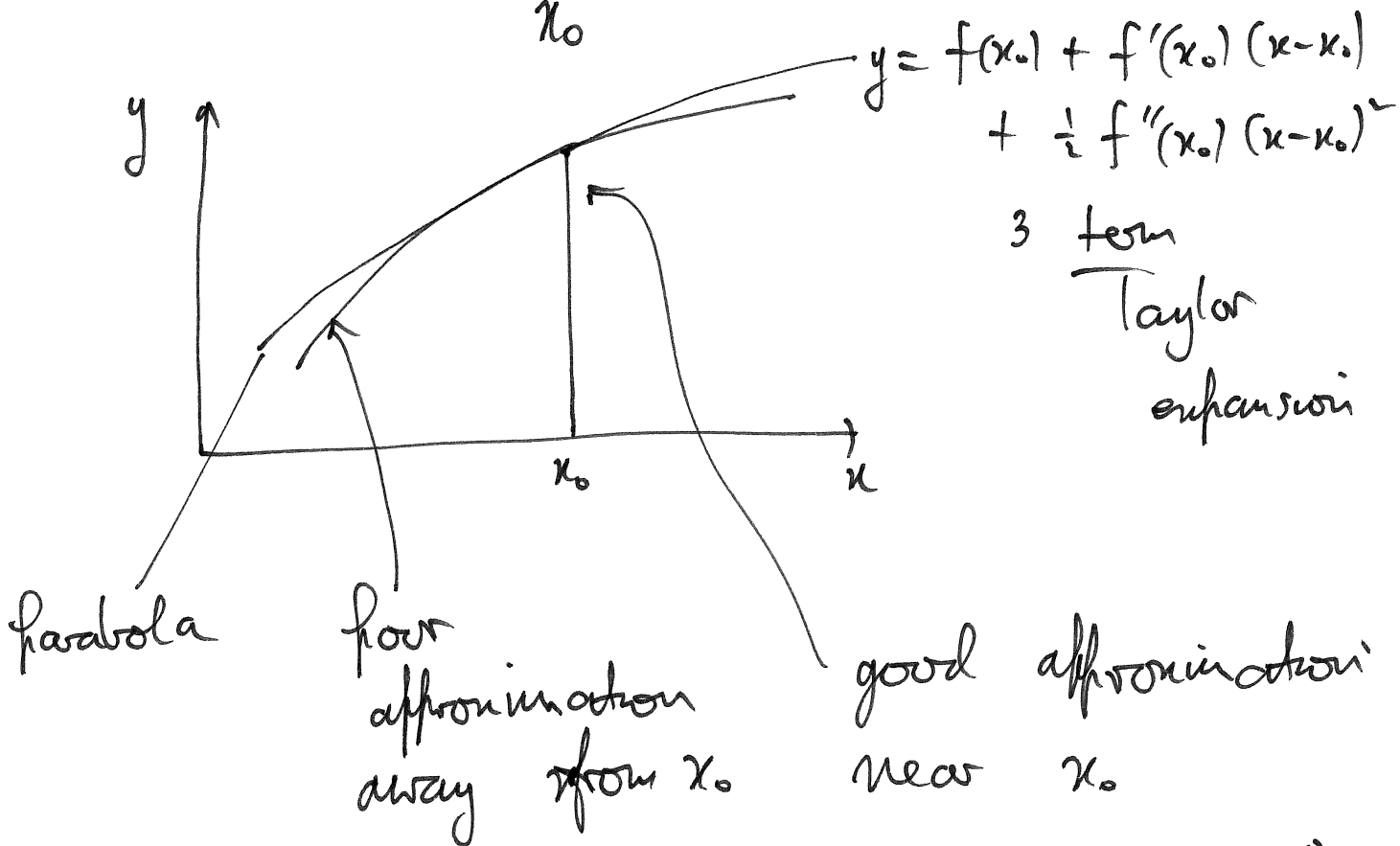
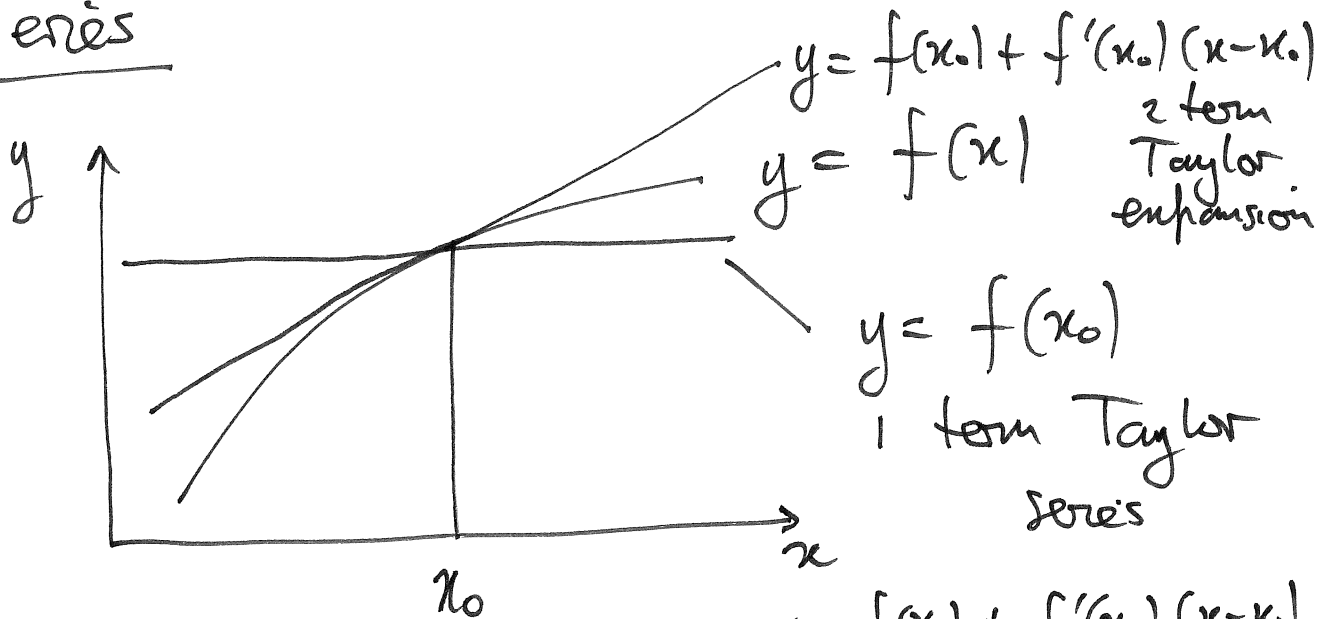
By the Intermediate Value Theorem
there exists η , $a < \eta < b$, such that

$$f(\eta) = \frac{\int_a^b f(x) g(x) dx}{\int_a^b g(x) dx}.$$

In these theorems the actual
determination of η is usually
extremely difficult.

Graphical Interpretation of Taylor Series

Series



Taylor polynomials are oscillatory ("kiss")

Remarks

- * Polynomials are easy to compute:
 $\times, +, -$ (no \div)
- * Polynomials are easy to differentiate & integrate.
- * Polynomial approximations may be easy to construct eg Taylor series.
- * Other polynomial approximations are possible besides Taylor series:
min-max approximations
orthogonal polynomials
- * More complicated functions than polynomials can be used to approximate other functions:
rational functions, trigonometric functions (Fourier series), etc.

10 Example of Taylor Expansion

$$f(x) = f(x_0) + f'(x_0)(x-x_0) + \frac{1}{2!} f^{(2)}(x_0)(x-x_0)^2 \\ + \dots + \frac{1}{n!} f^{(n)}(x_0)(x-x_0)^n \\ + \frac{1}{(n+1)!} f^{(n+1)}(\eta)(x-x_0)^{n+1}$$

where η lies between x & x_0 .

$$f(x) = \sin x, \quad x_0 = 1, \quad n = 2$$

$$f(1) = \sin 1$$

$$f^{(1)}(x) = \cos x$$

$$f^{(1)}(1) = \cos 1 \quad (f' \equiv f^{(1)})$$

$$f^{(2)}(x) = -\sin x$$

$$f^{(2)}(1) = -\sin 1$$

$$f^{(3)}(x) = -\cos x$$

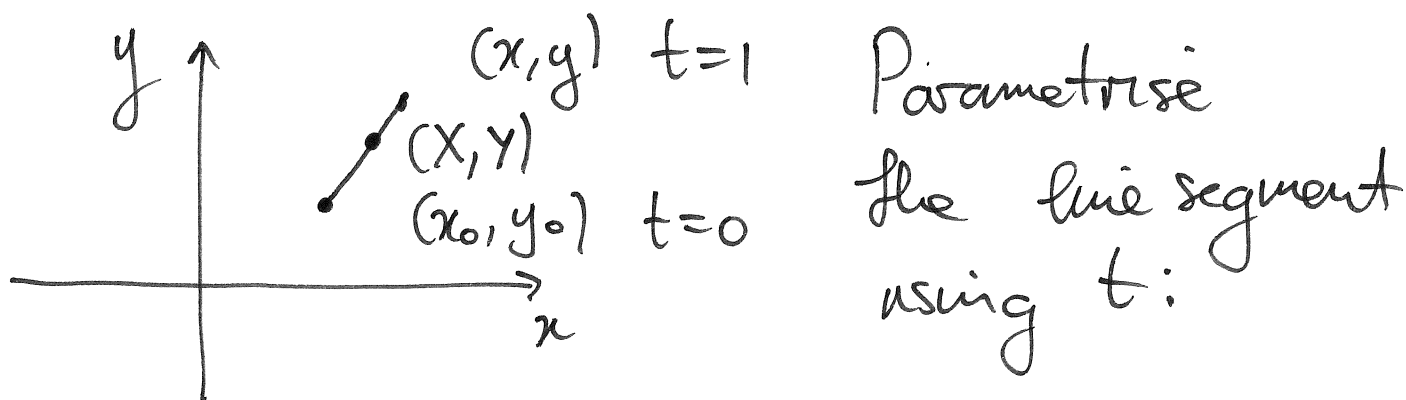
$$f^{(3)}(\eta) = -\cos \eta$$

Therefore the 3 term Taylor series for $\sin x$ about $x=1$ is

$$\sin x = \sin 1 + \cos 1 (x-1) + \frac{1}{2} (-\sin 1) (x-1)^2 \\ + \frac{1}{6} (-\cos \eta) (x-1)^3$$

$$\sin x = \sin 1 + \cos 1 (x-1) - \frac{1}{2} \sin 1 (x-1)^2 \\ - \frac{1}{6} \cos \eta (x-1)^3$$

Taylor Series for $F(x,y)$



$$X = x_0 + t(x - x_0)$$

$$Y = y_0 + t(y - y_0)$$

$$t=0: X = x_0, Y = y_0$$

$$t=1: X = x, Y = y.$$

Define the 1D function

$$F(t) := f(X, Y)$$

"is defined by"

$$= f(x_0 + t(x - x_0), y_0 + t(y - y_0))$$

Apply the 1D Taylor theorem to

$$F(t):$$

$$F(t) = F(0) + \frac{dF}{dt}(0)t + \frac{1}{2} \frac{d^2F}{dt^2}(0) t^2 + \dots$$

$$F(0) = f(x_0, y_0)$$

$$\frac{dF}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$$

$$= \frac{\partial f}{\partial x} (x - x_0) + \frac{\partial f}{\partial y} (y - y_0)$$

$$\therefore \frac{dF}{dt}(0) = \frac{\partial f}{\partial x}(x_0, y_0) (x - x_0) + \frac{\partial f}{\partial y}(x_0, y_0) (y - y_0) + \dots$$

Hence

$$F(t) = f(x_0, y_0) + \left[\frac{\partial f}{\partial x}(x_0, y_0) (x - x_0) + \frac{\partial f}{\partial y}(x_0, y_0) (y - y_0) \right] t + \dots$$

$$\begin{aligned} F(1) &= f(x_0, y_0) + \left[\frac{\partial f}{\partial x}(x_0, y_0) (x - x_0) + \frac{\partial f}{\partial y}(x_0, y_0) (y - y_0) \right] + \dots \\ &= f(x, y). \end{aligned}$$

Taylor's theorem for 2 functions of 2 variables (to 2 terms)

$$f_1(x_1, x_2) = f_1(x_1^0, x_2^0) + \frac{\partial f_1}{\partial x_1}(x_1^0, x_2^0)(x_1 - x_1^0) + \frac{\partial f_1}{\partial x_2}(x_1^0, x_2^0)(x_2 - x_2^0) + \dots$$

by Taylor's theorem for 1 function of 2 variables.

Similarly,

$$f_2(x_1, x_2) = f_2(x_1^0, x_2^0) + \frac{\partial f_2}{\partial x_1}(x_1^0, x_2^0)(x_1 - x_1^0) + \frac{\partial f_2}{\partial x_2}(x_1^0, x_2^0)(x_2 - x_2^0) + \dots$$

$$\underline{f}(\underline{x}) = \begin{bmatrix} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{bmatrix} = \begin{bmatrix} f_1(x_1^0, x_2^0) \\ f_2(x_1^0, x_2^0) \end{bmatrix} +$$

$$\begin{bmatrix} \frac{\partial f_1}{\partial x_1}(x_1^0, x_2^0) & \frac{\partial f_1}{\partial x_2}(x_1^0, x_2^0) \\ \frac{\partial f_2}{\partial x_1}(x_1^0, x_2^0) & \frac{\partial f_2}{\partial x_2}(x_1^0, x_2^0) \end{bmatrix} \begin{bmatrix} x_1 - x_1^0 \\ x_2 - x_2^0 \end{bmatrix} + \dots$$

$$= \underline{f}(\underline{x}_0) + \underline{J}(\underline{x}_0)(\underline{x} - \underline{x}_0) + \dots$$

where $\underline{J} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{bmatrix}$ is the Jacobian matrix of \underline{f} .