

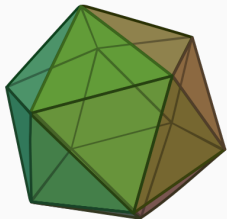
REPRESENTATION THEORY AND GEOMETRY

Geordie Williamson

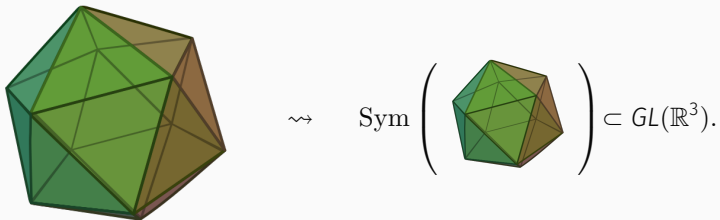
University of Sydney

<http://www.maths.usyd.edu.au/u/geordie/Heilbronn.pdf>

REPRESENTATIONS

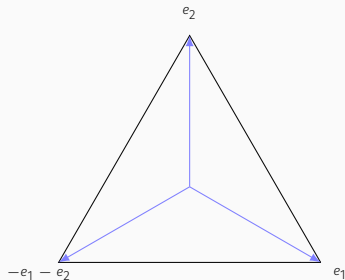


$$\rightsquigarrow \operatorname{Sym} \left(\text{polyhedron} \right) \subset GL(\mathbb{R}^3).$$



We obtain a **representation** of our group of symmetries

$$\rho : G \rightarrow GL(V).$$



$$\left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 & -1 \\ 0 & -1 \end{pmatrix}, \begin{pmatrix} -1 & 0 \\ -1 & 1 \end{pmatrix}, \begin{pmatrix} 0 & -1 \\ 1 & -1 \end{pmatrix}, \begin{pmatrix} -1 & 1 \\ -1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right\}$$

WHY STUDY REPRESENTATIONS?

Symmetric group S_n

The problem of understanding

$$\{S_n\text{-sets}\}/\text{isomorphism} \leftrightarrow \{\text{subgroups of } S_n\}/\text{conjugation}$$

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Galois representations

The passage(s)

$$\{\text{varieties}/\mathbb{Q}\} \longrightarrow \{\text{Galois representations}\}$$

is one of the most powerful tools of modern number theory.

Cayley's dictum that "a group is defined by means of the laws of combination of its symbols" would imply that, in dealing purely with the theory of groups, no more concrete mode of representation should be used than is absolutely necessary. It may then be asked why, in a book which professes to leave all applications on one side, a considerable space is devoted to substitution groups; while other particular modes of representation, such as groups of linear transformations, are not even referred to. My answer to this question is that while, in the present state of our knowledge, many results in the pure theory are arrived at most readily by dealing with properties of substitution groups, it would be difficult to find a result that could be most directly obtained by the consideration of groups of linear transformations.

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PREFACE TO THE SECOND EDITION

VERY considerable advances in the theory of groups of finite order have been made since the appearance of the first edition of this book. In particular the theory of groups of linear substitutions has been the subject of numerous and important investigations by several writers; and the reason given in the original preface for omitting any account of it no longer holds good.

In fact it is now more true to say that for further advances in the abstract theory one must look largely to the representation of a group as a group of linear substitutions. There is accordingly in the present edition a large amount of new matter.

Preface to **second edition**: Burnside, "Theory of groups of finite order", Cambridge University Press, **1912**.

Example

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A representation is **semi-simple** if it is isomorphic to a direct sum of simple representations.

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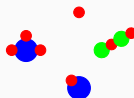
$$0 \subset L \subset H \subset \mathbb{F}_3^3.$$

We write (“Grothendieck group”, “**multiplicities**”)

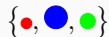
$$[\mathbb{F}_3^3] = [L] + [H/L] + [\mathbb{F}_3^3/H] = 2[\text{trivial}] + [\text{sign}].$$



representations \leftrightarrow “matter”



simple representations \leftrightarrow “elements”

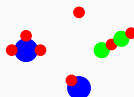


semi-simple \leftrightarrow “elements don’t interact”



SIMPLE REPRESENTATIONS

representations \leftrightarrow “matter”



simple representations \leftrightarrow “elements”



semi-simple \leftrightarrow “elements don’t interact”



We search for a **classification** (“periodic table”), **character formulas** (“mass”, “number of neutrons”), ...

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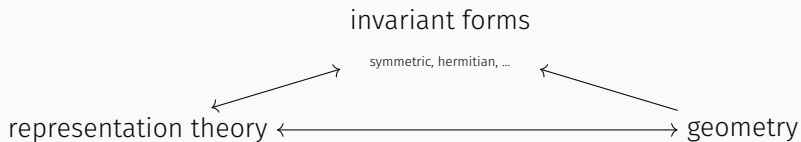
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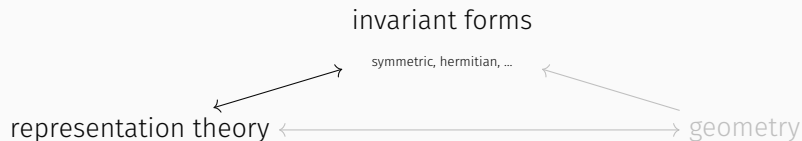
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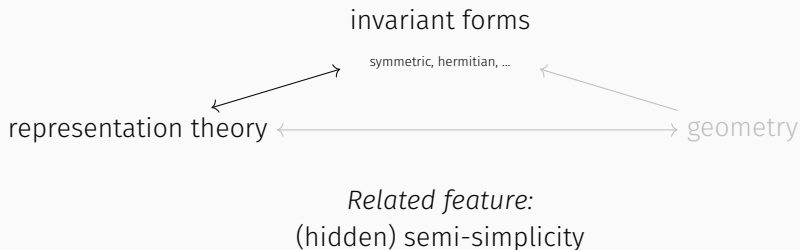
Related situations: non-compact Lie groups, p -adic groups...

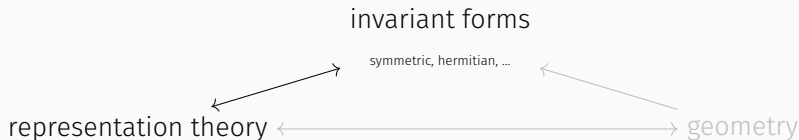
representation theory

representation theory \longleftrightarrow geometry





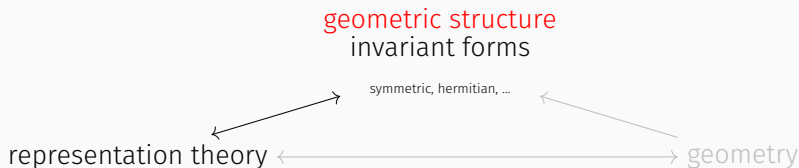




Related feature:
(hidden) semi-simplicity

A **geometric structure** on a real (resp. complex) vector space V will mean a non-degenerate symmetric (resp. Hermitian) form on V .

We do not assume that our forms are positive definite; **signature** plays an important role throughout.



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THE SEMI-SIMPLE WORLD

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If $U \subset V$ is a subrepresentation, then $V = U \oplus U^\perp$.

Observation 2: Any representation of G admits a positive-definite geometric structure.

Take a positive-definite geometric structure $\langle -, - \rangle$ on V . Then

$$\langle v, w \rangle_G := \frac{1}{|G|} \sum \langle gv, gw \rangle$$

defines a positive-definite and G -invariant geometric structure.

Example of “semi-simplicity via introduction of geometric structure”.

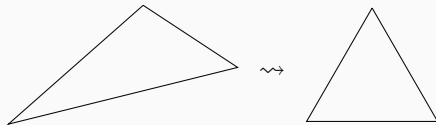
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This is an example of “unicity of geometric structure”.



Consider a compact Lie group K , e.g. S^1 or SU_2 or a finite group.

Weyl generalised these observations to K , with sum replaced by integral:

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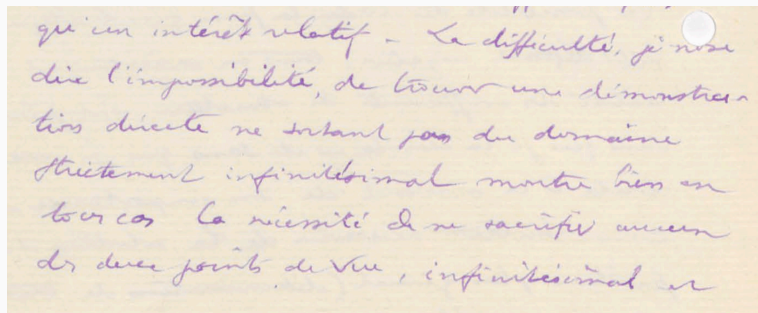
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Any continuous representation of a compact Lie group K is semi-simple.

Existence and uniqueness of geometric structure still holds.

Élie Cartan to Hermann Weyl, 28 of March 1925:



qu'un intérêt relatif - La difficulté, je n'ose
dire l'impossibilité, de trouver une démonstration
directe ne sortant pas du domaine
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"...the difficulty, I dare not say the impossibility, of finding a proof which does not leave the strictly infinitesimal domain shows the necessity of not sacrificing either point of view ..."

An algebraic ("infinitesimal") proof took 10 years, and involves the Casimir element (arises from an invariant form called the trace form).

“the wish to understand what really is the mathematical substance behind the formal apparatus of relativity theory led me to the study of representations and invariants of groups”. Hermann Weyl, 1949.

EXTENDED EXAMPLE: SU_2 AND \mathfrak{sl}_2

$$SU_2 = \left\{ A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mid AA^* = \text{id}, \det A = 1 \right\} = \text{unit quaternions.}$$

$$\text{Lie}(SU_2)_{\mathbb{C}} = \mathfrak{sl}_2(\mathbb{C}) = \mathbb{C} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \oplus \mathbb{C} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \oplus \mathbb{C} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

\parallel \parallel \parallel
 f h e

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"I don't think it is the representations themselves, but the groups. I find SU_2 , SL_2 , S_n etc. amazing and beautiful animals (if I have a favourite, it is SU_2), but will probably never really understand them. I might someday understand their linear shadows though..."

– Quindici

SU_2 acts on its “natural representation”:

$$\mathbb{C}^2 = \mathbb{C} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \oplus \mathbb{C} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \mathbb{C}Y \oplus \mathbb{C}X.$$

For any $m \geq 0$, SU_2 acts naturally on homogenous polynomials in X, Y of degree m :

$$L_m := \mathbb{C}Y^m \oplus \mathbb{C}Y^{m-1}X \oplus \cdots \oplus \mathbb{C}Y^mX^{m-1} \oplus \mathbb{C}X^m.$$

The L_m for $m \geq 0$ are all irreducible representations of SU_2 .

“spherical harmonics”, “quantum mechanics”.

Differentiate to get representation of the (complexified) Lie algebra

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Action on L_m (here $m = 5$):

$\mathbb{C}Y^5$

$\mathbb{C}Y^4X^1$

$\mathbb{C}Y^3X^2$

$\mathbb{C}Y^2X^3$

$\mathbb{C}YX^4$

$\mathbb{C}X^5$

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γ^5	$\gamma^4 X^1$	$\gamma^3 X^2$	$\gamma^2 X^3$	γX^4	X^5	
						
-5	-3	-1	1	3	5	h

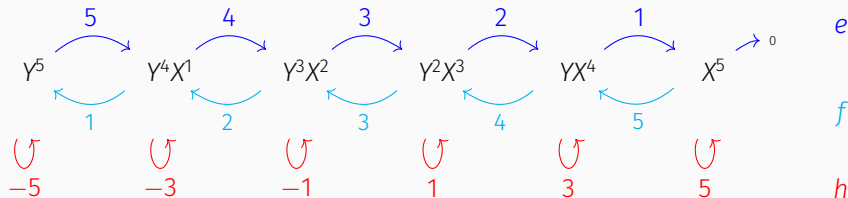
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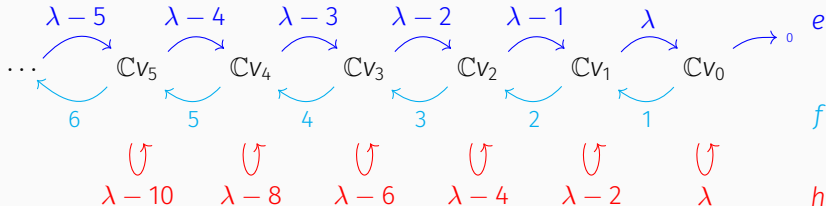
As vector spaces:

$$\Delta_\lambda = \bigoplus_{i \in \mathbb{Z}_{\geq 0}} \mathbb{C} v_i$$

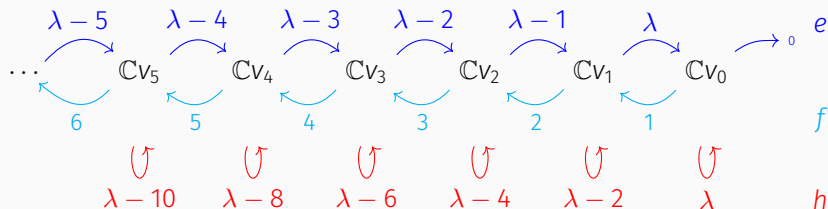
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The Verma module Δ_λ determined by $\lambda \in \mathbb{C}$:



STRUCTURE OF VERMA MODULES



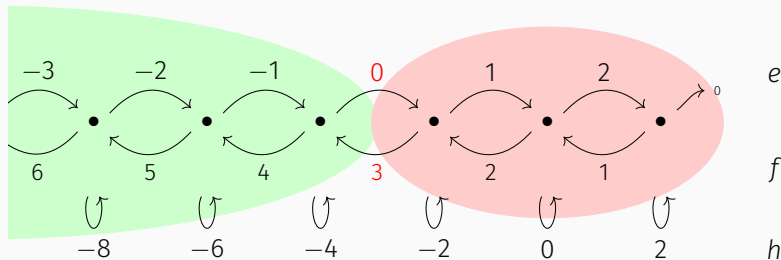
$\lambda \neq 0, 1, 2, 3, \dots$: Δ_λ is simple, call it L_λ .



$\lambda = 0, 1, 2, 3, \dots$: Δ_λ is not simple.



Example $\lambda = 2$



We have a subrepresentation isomorphic to Δ_{-4} , and

$$\Delta_2 / \Delta_{-4} \cong L_2$$



(L_2 is our simple finite-dimensional representation from earlier.)

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λ

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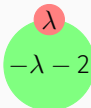
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Summary:

- (a) A single family of representations (Verma modules) produces all simple finite-dimensional representations.

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Summary:

- (a) A single family of representations (Verma modules) produces all simple finite-dimensional representations.
- (b) We get new infinite-dimensional simple representations.

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$-\lambda - 2$

Summary:

- (a) A single family of representations (Verma modules) produces all simple finite-dimensional representations.
- (b) We get new infinite-dimensional simple representations.
- (c) The structure of Verma modules varies (subtly) based on the parameter.

KAZHDAN-LUSZTIG CONJECTURE

\mathfrak{g} is a complex semi-simple Lie algebra.

$\mathfrak{h} \subset \mathfrak{g}$ a **Cartan** subalgebra.

W the **Weyl** group, which acts on \mathfrak{h} as a **reflection** group.

Example

$\mathfrak{g} = \mathfrak{sl}_n(\mathbb{C}) = \{ n \times n \text{ matrices } X \mid \text{tr} X = 0 \}.$

$\mathfrak{h} = \text{diagonal matrices} \subset \mathfrak{sl}_n(\mathbb{C})$

$W = S_n$ acting on \mathfrak{h} via permutations.

\mathfrak{g} is a complex semi-simple Lie algebra.

$\mathfrak{h} \subset \mathfrak{g}$ a **Cartan** subalgebra.

W the **Weyl** group, which acts on \mathfrak{h} as a **reflection** group.

Example

$\mathfrak{g} = \mathfrak{sl}_n(\mathbb{C}) = \{ n \times n \text{ matrices } X \mid \text{tr} X = 0 \}.$

$\mathfrak{h} = \text{diagonal matrices} \subset \mathfrak{sl}_n(\mathbb{C})$

$W = S_n$ acting on \mathfrak{h} via permutations.

Motivation

We think of the finite group W as being the **skeleton** of \mathfrak{g} .

We try to answer questions about \mathfrak{g} in terms of W .

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If $\lambda \neq 0, 1, \dots$, $L_\lambda = \Delta_\lambda$ is infinite dimensional.

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Basic problem

Describe the structure of Δ_λ .

Which simple modules occur with which multiplicity?

Δ_λ : Verma module. L_λ : simple highest weight module.

Kazhdan-Lusztig conjecture (1979)

$$[\Delta_\lambda] = \sum_{\mu} P_{\lambda,\mu}(1)[L_\mu].$$

Here $P_{\lambda,\mu} \in \mathbb{Z}[v]$ is a **Kazhdan-Lusztig** polynomial.

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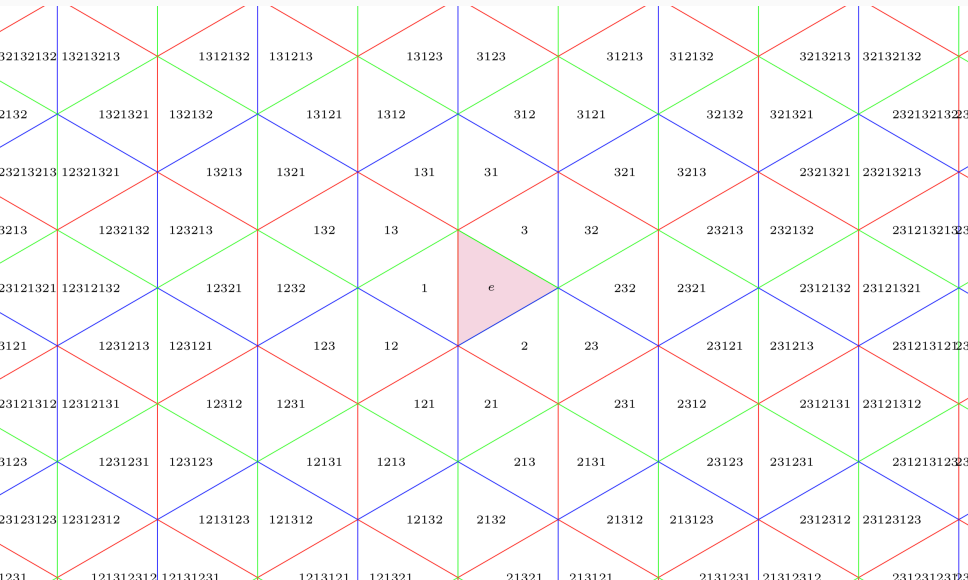
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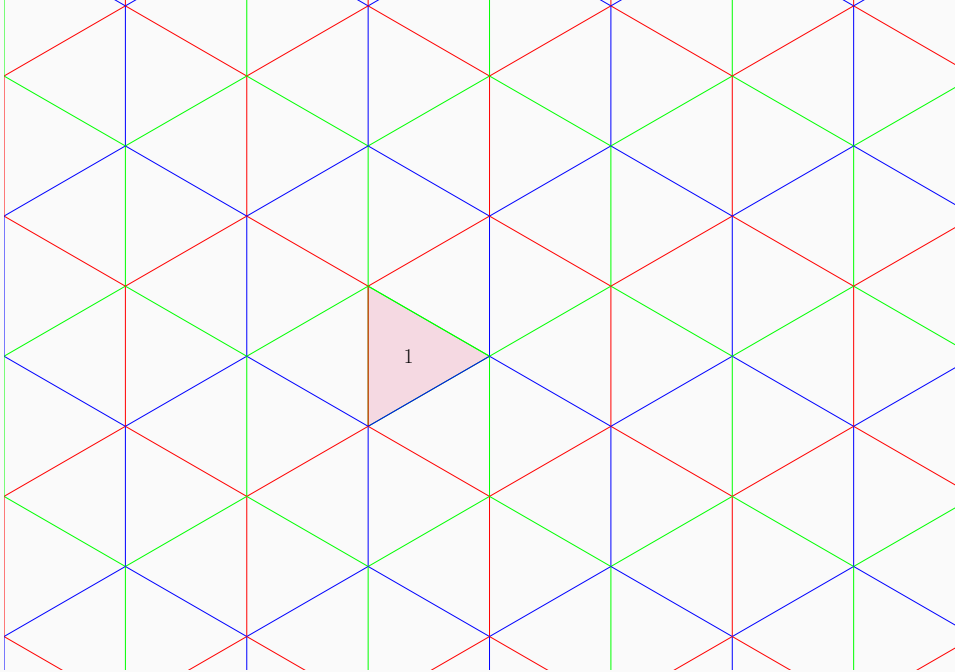
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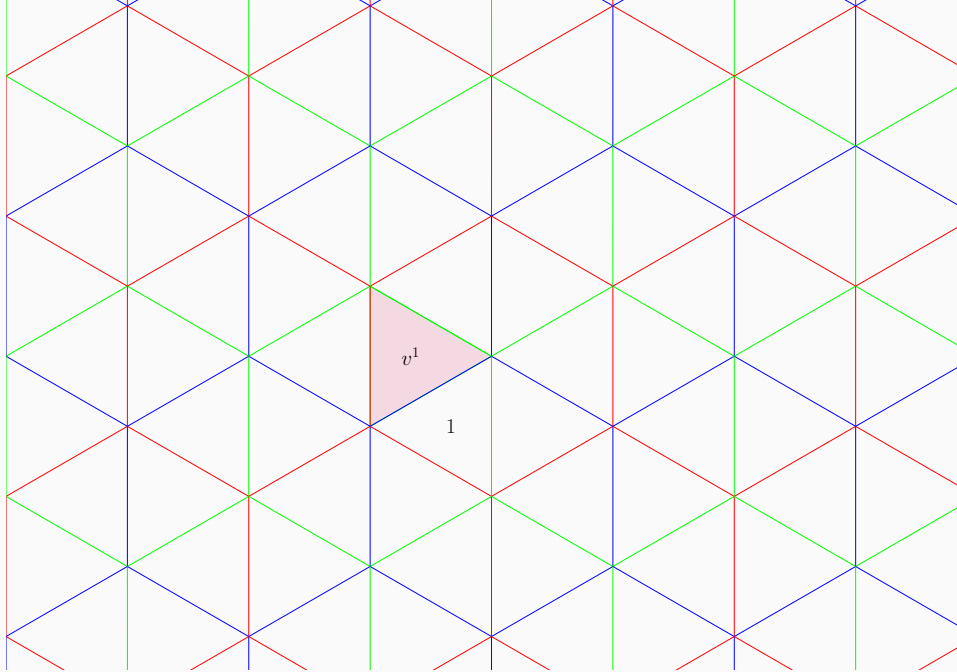
$$[\Delta_{x \cdot 0}] = \sum_{y \in W} P_{x \cdot 0, y \cdot 0}(1) [L_{y \cdot 0}].$$

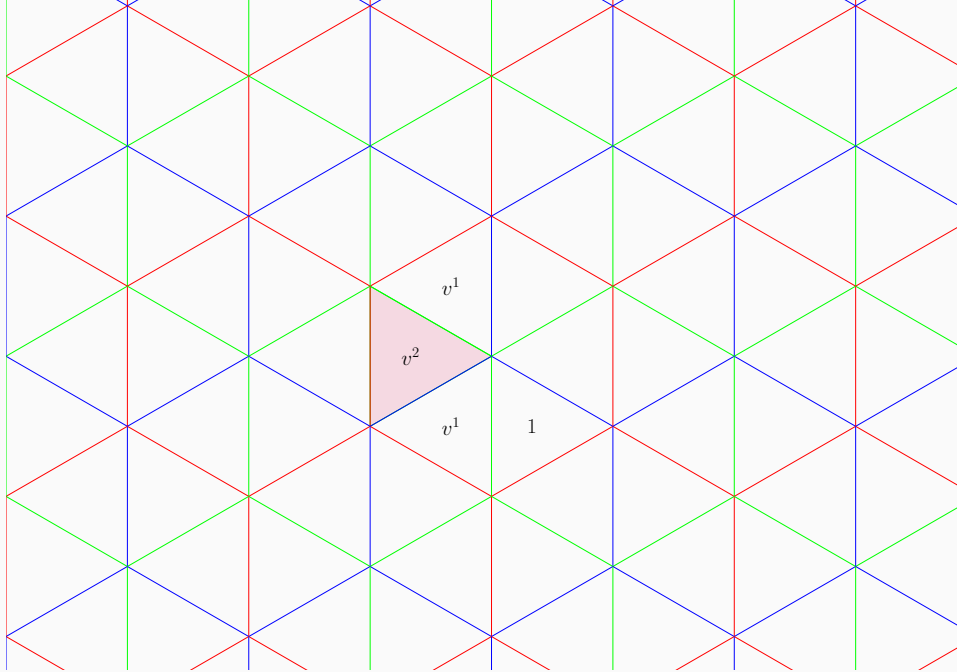
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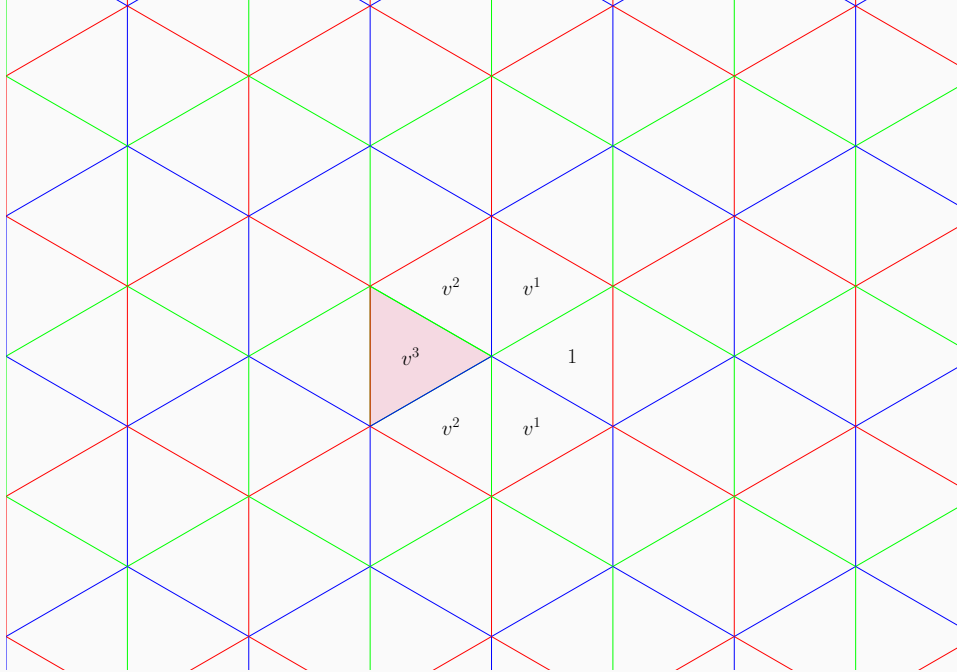
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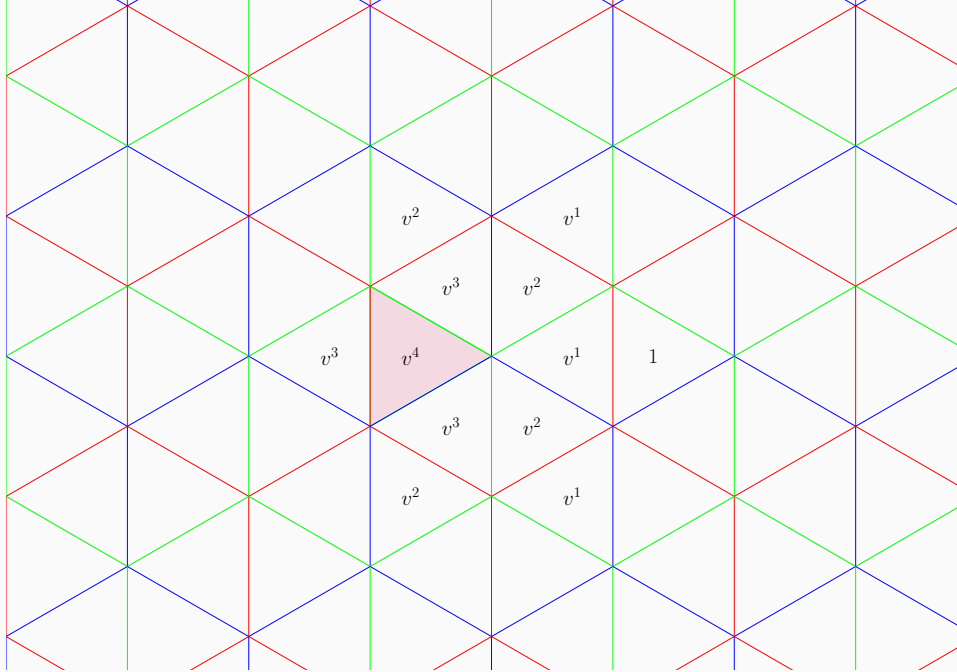


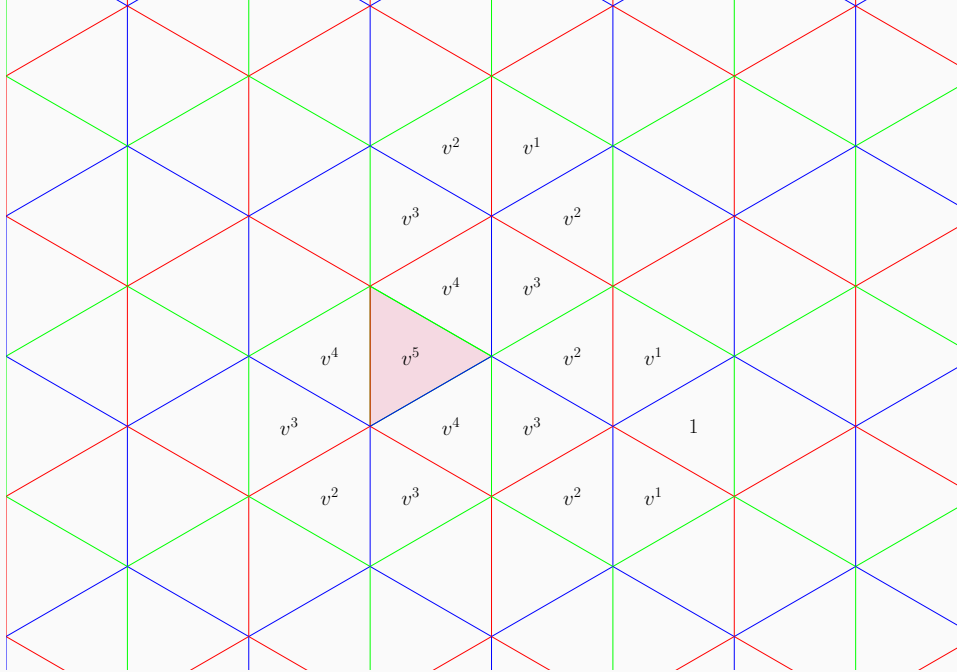


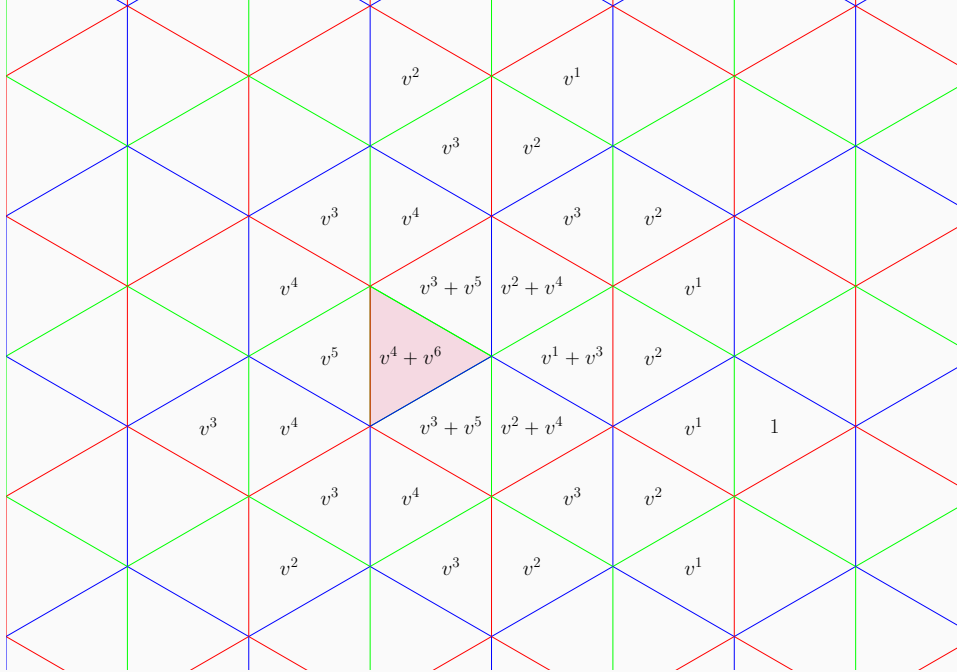


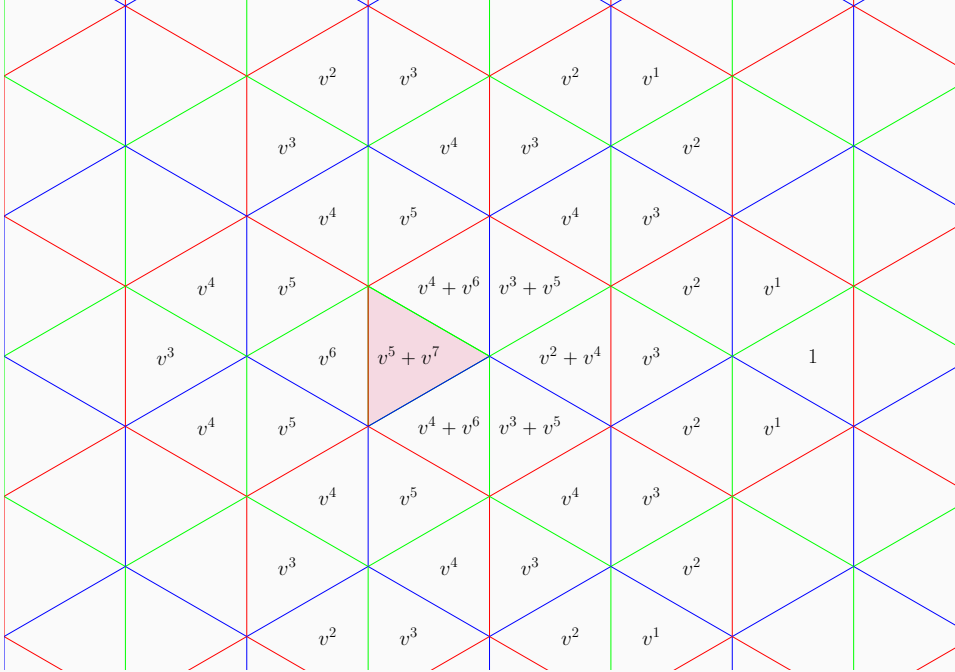


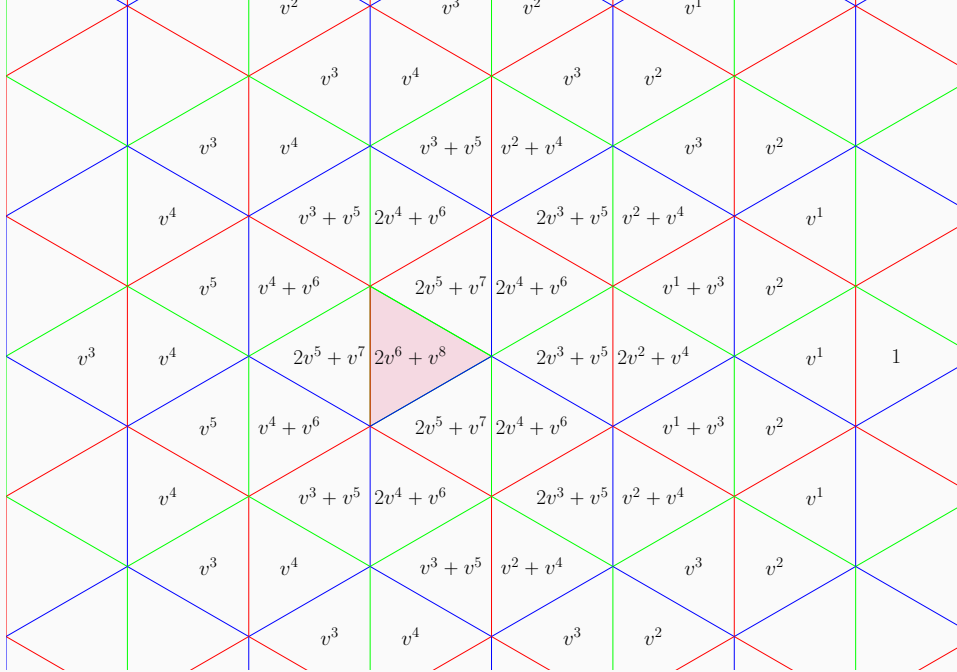












JANTZEN CONJECTURE

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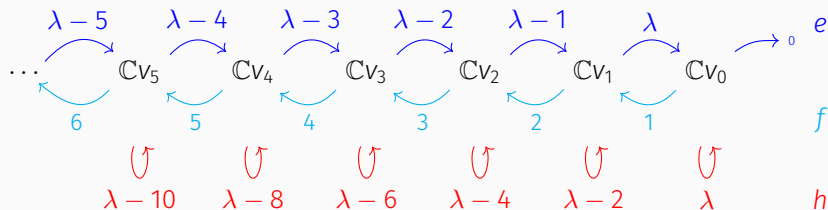
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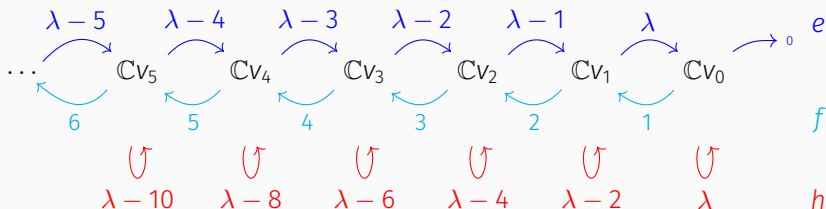
I will now explain the relevance of the **contravariant form** to the Kazhdan-Lusztig conjecture.

This will end up explaining why there is a q in the Kazhdan-Lusztig conjecture.

Our Verma module for \mathfrak{sl}_2 from earlier:



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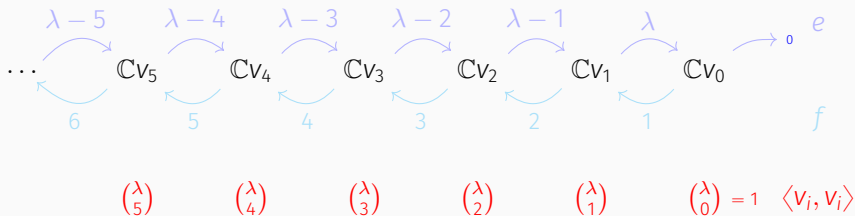


There is a unique symmetric form (the **contravariant form**) satisfying

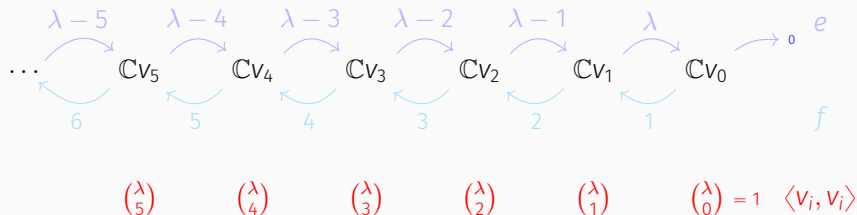
$$\langle v_0, v_0 \rangle = 1,$$

$$\langle hv, v' \rangle = \langle v, hv' \rangle \quad \text{and} \quad \langle ev, v' \rangle = \langle v, fv' \rangle.$$

THE CONTRAVARIANT FORM



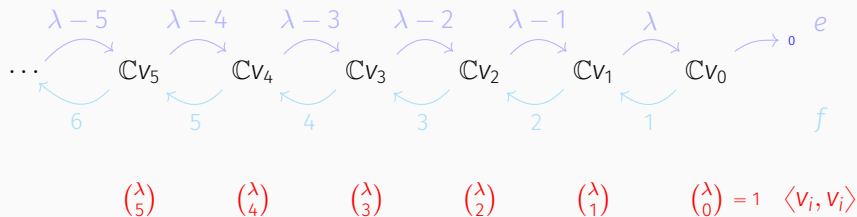
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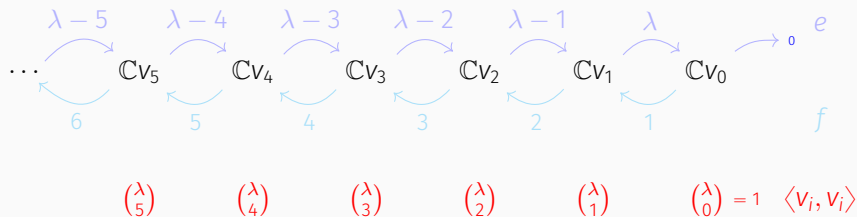
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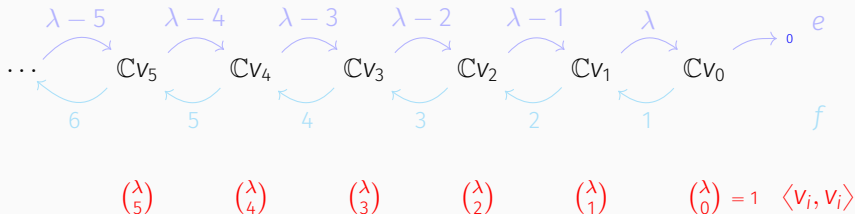
The contravariant form is non-degenerate if and only if $\binom{\lambda}{i} \neq 0$ for all $i \geq 0$, which is the case if and only if λ is not a non-negative integer.

THE CONTRAVARIANT FORM



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We have seen that this is precisely the condition for Δ_λ to be irreducible.

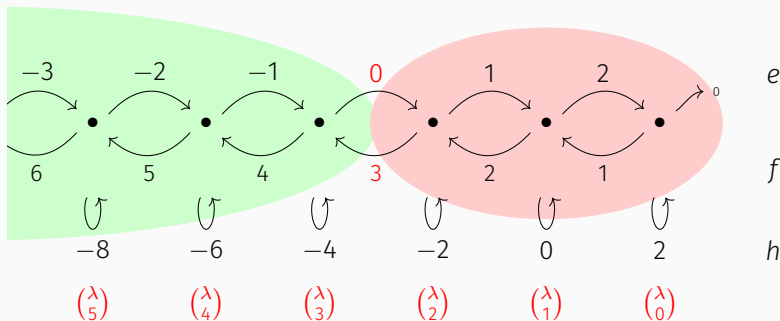


Jantzen's beautiful idea

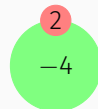
View the form $\langle -, - \rangle$ as a family of forms depending on the parameter λ . Then study the vanishing behaviour of this form.

VANISHING OF THE CONTRAVARIANT FORM

Example $\lambda = 2$



At $\lambda = 2$, the contravariant form vanishes to order 1 precisely on the subrepresentation Δ_{-4} identified earlier.



Verma modules and their contravariant forms give a family over \mathfrak{h}^* .

\rightsquigarrow **Jantzen filtration** via order of vanishing of contravariant form:

$$\Delta_\lambda \supset F^1 \Delta_\lambda \supset F^2 \Delta_\lambda \supset \dots$$

Subquotients $F^i \Delta_\lambda / F^{i+1} \Delta_\lambda$ admit non-degenerate forms.

Jantzen conjecture (1979)

The subquotients $F^i \Delta_\lambda / F^{i+1} \Delta_\lambda$ are **semi-simple**.

“although Verma modules are not semi-simple, the layers of the Jantzen filtration do not interact”

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- Explains why Kazhdan-Lusztig polynomials are **polynomials**:

$$(\Delta_\lambda : L_\mu) = P_{\lambda,\mu}(1) \quad \rightsquigarrow \quad \sum_i (\mathrm{gr}_F^i \Delta_\lambda : L_\mu) q^i = P_{\lambda,\mu}$$

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- Instance of “**hidden semi-simplicity**”.
- Important in unitarity problem for real Lie groups (signature).

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Beilinson-Bernstein

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Geometric proofs: D -modules, perverse sheaves, weights...

Algebraic proofs: “shadows of Hodge theory”,
i.e. invariant forms (“geometric structures”)
still satisfying Poincaré duality, Hard Lefschetz, Hodge-Riemann